



LEAF WOOD SEPARATION OF TLS POINT CLOUD OF MANGROVES

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Background



Mangroves grow in hostile environments – marshy and saline.

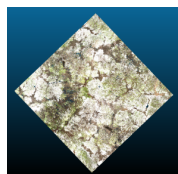
Terrestrial Laser Scanner (TLS) captures 3D details of forests actively and accurately.

Retrieval of biophysical parameters like tree height, AGB, canopy cover, etc. requires separation of point clouds into wood and leaves.

Traditional foliage filtering methods produce erroneous results when applied to TLS point clouds of mangroves.



Materials

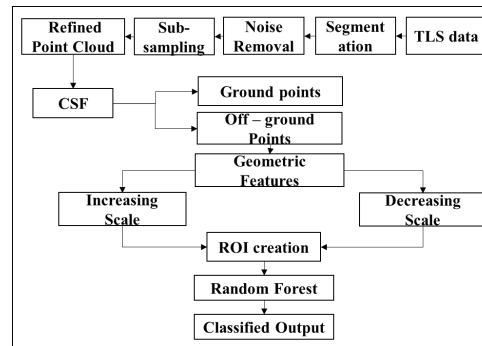


Faro Focus S 350 TLS at 1550nm wavelength was used to collect point cloud data from a 33m x 33m plot (72.81897 19.23719) in Gorai, Maharashtra, India.

Research Goals

- (i) To find a method to separate the leaves from wood of raw point cloud data, (ii) to find features substantial to the process, and (iii) to find the spatial scales at which the inter-class separability is maximum.

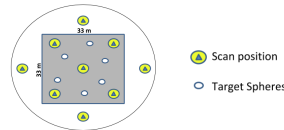
Methodology



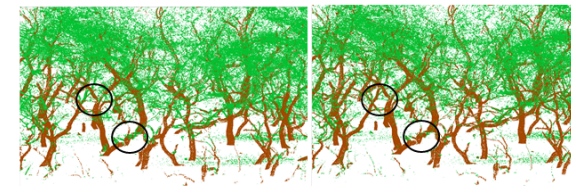
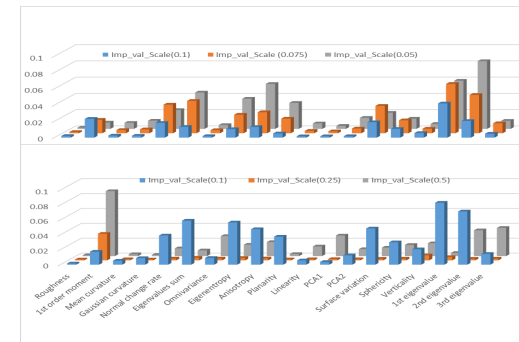
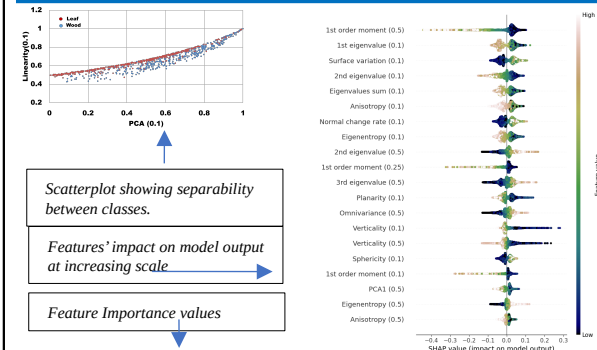
CSF – Cloth Simulation Filter, Increasing scale - 0.1m, 0.25m, and 0.5m & decreasing scale - 0.1m, 0.075m, and 0.05m

Features extracted at both sets of scales (19*3)

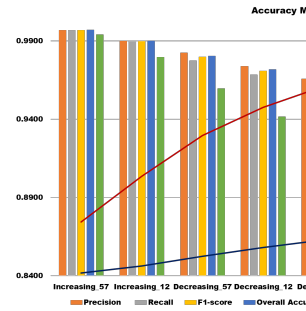
1st eigenvalue, 2nd eigenvalue, 3rd eigenvalue, verticality, sphericity, surface variation, linearity, planarity, anisotropy, roughness, eigenentropy, omnivariance, sum of eigenvalues, normal change rate, gaussian curvature, mean curvature, first-order moment and the first two principal components.



Results



Classified output (left) decreasing scale, (right) increasing scale.



Discussion

- Features at increasing scale components better than features at decreasing scale.
- Features having most impact on model output are 1st and 2nd eigenvalues sum, anisotropy, and planarity.

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References

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- Adimoolam, Y. K., Pillai, N. D., Kumar, V. (2022). Estimation of Above-ground Biomass of Mangrove Forests from Terrestrial LiDAR Point Clouds using Machine Learning Algorithms.
- Vicari, M. B., Disney, M., Wilcock, T., Woodgate, W. (2019). Leaf and wood separation of terrestrial LiDAR point clouds. *Remote Sensing*, 11(5), 680-694.